Reconstruct radio map for indoor localization

Part1: introduction

Part2: radio propagation model

Part3: model based approach for fingerprints reconstruction

Part4:simulation in MATLAB

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PART1: INTRODUCTION

- The main theory is based on the previous persons' work.
- Indoor localization has been under intensive investigations in recent years.
- The Wi-Fi fingerprints based approach is very popular.



MAIN PROBLEM

• How to get the RSS fingerprints efficiently.

Related work:

- Compressive Sensing
- Fingerprint based Indoor Localization
- Model based Approach





• Single-step radio propagation model



• Some assumption

- 1. x:the power level of the signal at the center of the square
- 2. y:the aggregate power level after the walls' effects
- 3. α the transmissivity of the wall ranging from 0 to 1
- We only consider the case where the signal can travel to the four neighboring cells for the simplicity of presentation.







• As shown before, we can get the single-step matrix H.

 $H_{i,j}$: the radio signal changes after it arrives to $cell_j$ from $cell_i$ in power level

- Properties of H matrix:
 - 1) $H_{i,j} = H_{j,i}$

2) for each roll in matrix H, there are at most four non-zero elements

PART3: MODEL BASED APPROACH FOR FINGERPRINTS RECONSTRUCTION

• T : the multi-hop radio propagation matrix

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$$T_{ij} = \sum_{k=1}^{n^2} (H_{ij} + H_{ik}H_{kj} + \dots + H_{ik}H_{km} \dots H_{pq}H_{qj})$$

H_{ik}H_{kj} describe the propagation process from *cell_i* to *cell_j* obeying Huygens' principle.

• Each elements of equation represents an independent channel form $cell_i$ to $cell_i$.

- $Tx = Hx + H^2x + H^3x + ...$
- $T = H + H^2 + H^3 + ...$
- $\mathbf{T} = (E H)^{-1}H$
- Get the H matrix through collected fingerprints at a limited number of locations.

Only $H_{i-1,j}$, $H_{i+1,j}$, $H_{i-n,j}$, $H_{i+n,j}$ are valid.

 $H_{i,i-1} = T_{i,i-1} - \sum_{k} H_{i,k} T_{k,i-1}$

 $= T_{i,i-1} - H_{i,i-n}T_{i-n,i-1} - H_{i,i-1}T_{i-1,i-1} - H_{i,i+1}T_{i+1,i-1} - H_{i,i+n}T_{i+n,i-1}$

$$\bullet \begin{bmatrix} 1 + T_{i-n,i-n} & T_{i-1,i-n} & T_{i+1,i-n} & T_{i+n,i-n} \\ T_{i-n,i-1} & 1 + T_{i-1,i-1} & T_{i+1,i-1} & T_{i+n,i-1} \\ T_{i-n,i+1} & T_{i-1,i+1} & 1 + T_{i+1,i+1} & T_{i+n,i+1} \\ T_{i-n,i+n} & T_{i-1,i+n} & T_{i+1,i+n} & 1 + T_{i+n,i+n} \end{bmatrix} \begin{bmatrix} H_{i,i-n} \\ H_{i,i-1} \\ H_{i,i+1} \\ H_{i,i+n} \end{bmatrix} = \begin{bmatrix} T_{i,i-n} \\ T_{i,i-1} \\ T_{i,i+1} \\ T_{i,i+n} \end{bmatrix}$$

As shown above: if x stand for the first subscript of T, and y stands for the second one. all we need is elements in matrix T that satisfy one of the equations as following: y = x, y = x + n, y = x - n, y = x + 1, y = x + 1, y = x - 1, y = x + 2, y = x - 2, y = x - 2n, y = x + 2n, y = x + 1 + n, y = x + 1 - n, y = x - 1 + n, y = x - 1 - n.

Part4:simulation in MATLAB

Step 1: generate the H matrix

function [H_matrix] = genH(n, sigma)

Step 2: generate the T matrix T= (E-H0)\H0;

Step 3: generate the T1 ,T2matrix T1 = [1,2,3,4;5,6,7,8;9,10,11,12;13,14,15,16]; T2 = zeros(4, 1);Step 4: generate the H1matrix Step 5: compare H1matrix with the original H

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errh=(H1-H0)./(H0+0.0001);

error_H=sum(sum(errh)/(n*n*n*n));

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- Further work:
- The simulation of the situation that there is an obstacle in the room

