

Gossip-based Truth Discovery

Zhiying Xu

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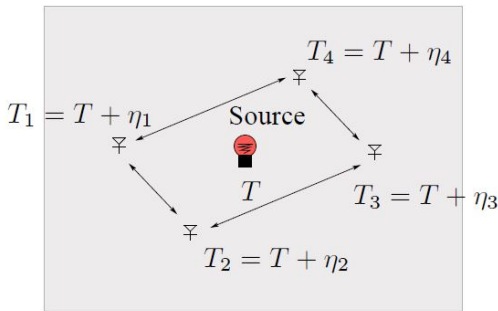
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Gossip Algorithm

Gossip algorithms: schemes which distribute the computation burden and in which a node communicates with a randomly chosen neighbor.



Truth Discovery

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- Discover truth from noisy crowd sensing data
- Evaluate the reliability of sensors

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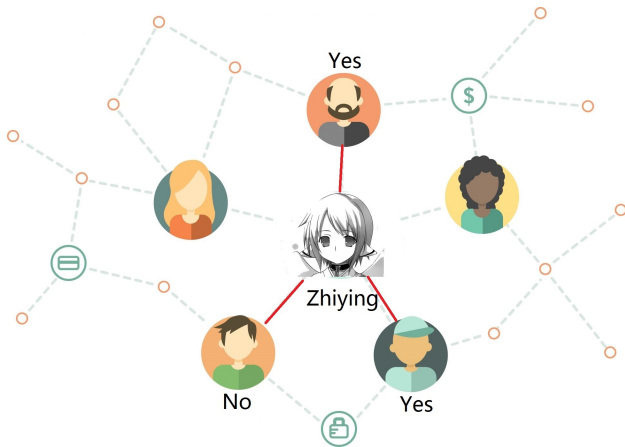
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A Real-life Case

Whether the class is canceled?



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Model

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Definition (Problem Formulation)

Given a crowd sensing model where N sensors make individual observations $\mathbf{X}^{N \times M} \in \{0, 1\}^{N \times M}$ about a set of M variables, determine the true value of these variables $\mathbf{t}^M \in \{0, 1\}^M$ which satisfies

$$\langle \mathbf{t}, \mathbf{r} \rangle = \arg \min_{\langle \mathbf{t}, \mathbf{r} \rangle} p(\mathbf{X} | \mathbf{t}, \mathbf{r}),$$

where $\mathbf{r}^N \in [0, 1]$ is the reliability of sensors.

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where $\mathbf{r}^N \in [0, 1]$ is the reliability of sensors.

- \mathbf{t}, \mathbf{r} are related to each other.
- There is no need for iteration by EM algorithm.

Objective Function

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Using the relationship between \mathbf{t} and \mathbf{r} , We can simplify the previous problem into the optimization of the objective function

$$\mathbf{t} = \arg \min_{\mathbf{t}} \sum_{i=1}^N f(\mathbf{x}_i, \mathbf{t}),$$

where $f(\mathbf{x}_i, \mathbf{t})$ denotes

$$\frac{\|\mathbf{x}_i - \mathbf{t}\|}{M} \ln \frac{M}{\|\mathbf{x}_i - \mathbf{t}\|} + \left(1 - \frac{\|\mathbf{x}_i - \mathbf{t}\|}{M}\right) \ln \left(1 - \frac{M}{\|\mathbf{x}_i - \mathbf{t}\|}\right).$$

Truth Discovery Strategy

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- All sensors are in a connected networks.
- Sensors have limited memory and can't store much data.
- Each sensor communicates with a random neighbor asynchronously.

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NP Hardness of the Decision Version

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Given a matrix $\mathbf{X}^{N \times M}$, is there a vector \mathbf{t}^M which satisfies $\sum_{i=1}^N f(\mathbf{x}_i, \mathbf{t}) < C$?

Proof of NP Hardness

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Theorem

Discovering the truth \mathbf{t} from the observed matrix \mathbf{X} is NP-hard.

- By reduction from 3 exact cover problem.
- Inspired by Cardinal, J., Fiorini, S. and Joret, G., 2012. Minimum entropy combinatorial optimization problems. Theory of Computing Systems, 51(1), pp.4-21.

Proof of NP Hardness

Proof: Step 1

3 exact cover: Given a set system (U, S) , decide whether U can be covered using pairwise disjoint sets from S



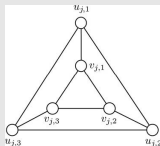
minimum orientation defined on a concave function:

Construct a graph by creating a gadget for each element in U .

Given the graph, decide whether there is an

orientation that satisfies $\sum_{i=1}^{|V|} g\left(\frac{d_i^+}{|E|}\right) < C_1$.

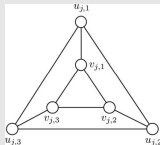
Here $g(\cdot)$ is a concave function and d_i^+ is the in-degree of the node i .



Proof of NP Hardness

Proof: Step 2

minimum orientation defined on a concave function:



Given the graph, decide whether there is an orientation that satisfies $\sum_{i=1}^{|V|} g\left(\frac{d_i^+}{|E|}\right) < C_1$. Here $g(\cdot)$ is a concave function and d_i^+ is the in-degree of the node i .



Truth Discovery:

Covert the graph into a matrix \mathbf{X} , decide whether there is a vector \mathbf{t}^M which satisfies $\sum_{i=1}^N f(\mathbf{x}_i, \mathbf{t}) < C_2$.

\mathbf{X} = ancillary part + graph part.

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The Complexity of Exact Algorithm

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Theorem

The complexity of the exact algorithm is $\Theta(2^{\text{rank}(\mathbf{X})})$.

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Theorem

The complexity of the exact algorithm is $\Theta(2^{\text{rank}(\mathbf{X})})$.

- The base vectors can be obtained in polynomial time.
- The truth vector \mathbf{t} is a combination of the base vectors of the observed vectors \mathbf{x}_i .

Exact Algorithm

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Algorithm 1 Exact Algorithm

Input: Observed matrix \mathbf{X}

Output: Truth vector \mathbf{t}

- 1: **Initialize:** $S_1 = 0, S_2 = N$
 - 2: Calculate the base vectors of \mathbf{X}
 - 3: **for** $\mathbf{t}^* \in$ combination of the base vectors **do**
 - 4: **for** $i = 1$ to n **do**
 - 5: $S_1 = S_1 + f(\mathbf{x}_i, \mathbf{t}^*)$
 - 6: **end for**
 - 7: **if** $S_1 < S_2$ **then**
 - 8: $S_2 = S_1, \mathbf{t} = \mathbf{t}^*$
 - 9: **end if**
 - 10: $S_1 = 0$
 - 11: **end for**
-

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Theorem

The approximation algorithm achieves an approximation ratio of 1.7.

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Theorem

The approximation algorithm achieves an approximation ratio of 1.7.

- The approximation ratio is an upper bound, for the worse case is difficult to find.
- Use triangle inequality $f(\mathbf{x}, \mathbf{y}) + f(\mathbf{y}, \mathbf{z}) > f(\mathbf{x}, \mathbf{z})$.
- The complexity is $\Theta(n^2)$

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Algorithm 2 Approximation Algorithm

Input: Observed matrix X

Output: Truth vector t

```
1: Initialize:  $S = 0, t_2 = 0$ 
2: Find the 1-median point  $t_1$  in metric space  $(\{0, 1\}^M, f)$ 
3: for  $i = 1$  to  $n$  do
4:   if  $\|x_i - t_1\|_1/M < \frac{1}{4}$  then
5:      $t_2 = t_2 + x_i$ 
6:   else if  $\|x_i - t_1\|_1/M > \frac{3}{4}$  then
7:      $t_2 = t_2 + \mathbf{1} - x_i$ 
8:   else
9:      $t_2 = t_2 + \frac{1}{2}\mathbf{1}$ 
10:  end if
11: end for
12:  $t_2 = \text{round}(t_2/N)$ 
13: if  $\sum_{i=1}^N f(x_i, t_1) > \sum_{i=1}^N f(x_i, t_2)$  then
14:    $t = t_2$ 
15: else
16:    $t = t_1$ 
17: end if
```

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Decentralized Exact Algorithm

- It's hard to calculate the base vectors in a decentralized ways, so we decide to try every vector in $\{0, 1\}^M$
- There is a trade-off between run time and accuracy.

$$\text{run time: } 2^M \frac{3 \log \epsilon^{-1}}{\log \lambda_2 (W_1)^{-1}}$$

$$W_1 = I - \frac{1}{2n} D + \frac{P + P^T}{2n}$$

$$D_i = \sum_{j=1}^n [P_{ij} + P_{ji}]$$

$$\text{accuracy: } 1 + 2\epsilon$$

Decentralized Exact Algorithm

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Algorithm 3 Decentralized Exact Algorithm

Input: Observed matrix X

Output: Truth vector t

- 1: **Initialize:** $f_{min_1} = N$
 - 2: **for** $t' \in \{0, 1\}^M$ **do**
 - 3: Every node calculates $f_i = f(x_i, t')$
 - 4: **for** $k = 1$ to $\frac{3 \log \epsilon^{-1}}{\log \lambda_2(W)^{-1}}$ **do**
 - 5: A node calculates the average f with its random neighbor and renews the values of both nodes
 - 6: **end for**
 - 7: **if** $f_i < f_{min}$ **then**
 - 8: $f_{min} = f_i, t = t'$
 - 9: **end if**
 - 10: **end for**
-

A Fast Algorithm for 1-median Problem

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- Using triangle inequality in metric space and Chebyshev Inequality
- Inspired by Indyk, P., 1999, May. Sublinear time algorithms for metric space problems. In Proceedings of the thirty-first annual ACM symposium on Theory of computing (pp. 428-434). ACM.

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Algorithm 4 Fast Algorithm for 1-median Problem

Input: Observed matrix \mathbf{X}

Output: 1-median Point \mathbf{x}^*

- 1: **Initialize:** $\mathbf{Y} = \mathbf{X}, \mathbf{Z} = [0]$
 - 2: **for** $k = 1$ to $\log^2 n 4(4/\sigma + 1)^2 / \sigma^2$ **do**
 - 3: Every node changes \mathbf{y}_i with a random neighbor asynchronously.
 - 4: For every mixing time $\frac{\log n + \log \epsilon^{-1}}{1 - \lambda_P}$,
 $Z_{i\|x_i - y_i\|_1} = Z_{i\|x_i - y_i\|_1} + 1$
 - 5: **end for**
 - 6: **for** $k = 1$ to $8(\ln 2 + 2 \ln n + \ln \epsilon^{-1}) / \Phi$ **do**
 - 7: For a node i compare with its random neighbor j ,
We only compare the sum of distance shorter than $4f(\mathbf{x}_i, \mathbf{x}_j) / \sigma$
 - 8: $\mathbf{x}_i = \mathbf{x}_j =$ the smaller one
 - 9: **end for**
 - 10: $\mathbf{x}^* = \mathbf{x}_i$
-

Decentralized Approximation Algorithm

- Implement the fast algorithm for 1-median problem.
- There is a trade-off between run time and accuracy.

$$\text{run time: } \frac{6 \log \epsilon_1^{-1}}{\log \lambda_2 (W_1)^{-1}} + \frac{\log^2 n 4 (4/\sigma + 1)^2 \log n + \log \epsilon_2^{-1}}{\sigma^2 (1 - \lambda_2 (W_2))}$$

$$8 \frac{\ln 2 + 2 \ln n + \ln \epsilon^{-1}}{\Phi}$$

$$W_2 = I - \frac{1}{n} D + \frac{P + P^T}{n}$$

$$D_i = \sum_{j=1}^n [P_{ij} + P_{ji}]$$

$$\text{accuracy: } \max \left\{ 1.5 + 4\epsilon_1, (1 + \epsilon_2 + \sigma) \frac{f(1/15/(1 + \epsilon_2 + \sigma))}{f(1/30/(1 + \epsilon_2 + \sigma))} \right\}$$

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Algorithm 5 Decentralized Exact Algorithm

Input: Observed matrix \mathbf{X}

Output: Truth vector \mathbf{t}

- 1: **Initialize:** $\mathbf{Y} = \mathbf{X}, \mathbf{Z} = [0]$
 - 2: Implement the fast algorithm for 1-median problem and get the \mathbf{x}^* .
 - 3: For every node i
 - 4: **if** $\|\mathbf{y}_i - \mathbf{x}^*\|_1/M < \frac{1}{4}$ **then**
 - 5: $\mathbf{z}_i = \mathbf{y}_i$
 - 6: **else if** $\|\mathbf{x}_i - \mathbf{t}_1\|_1/M > \frac{3}{4}$ **then**
 - 7: $\mathbf{z}_i = \mathbf{1} - \mathbf{y}_i$
 - 8: **else**
 - 9: $\mathbf{z}_i = \frac{1}{2}\mathbf{1}$
 - 10: **end if**
 - 11: Calculate the average of $\mathbf{z} = \text{round}(\mathbf{z}_i)$
 - 12: $\mathbf{t} = \arg \min_{\mathbf{x}^*, \mathbf{z}} \sum_{i=1}^N f(\mathbf{x}_i, \mathbf{t})$
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Convex Optimization of the Matrix

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minimize $\lambda_2(W)$

subject to $W = \sum_{i,j=1}^n \frac{1}{n} P_{ij} W_{ij}$

$$P \leq [0],$$

$$P_{ij} = 0 \text{ if } \{i, j\} \notin E,$$

$$\sum_j P_{ij} = 1, \forall i.$$

\Rightarrow

minimize s

subject to $W - \mathbf{1}\mathbf{1}^T/n \preceq sI$

$$W = \sum_{i,j=1}^n \frac{1}{n} P_{ij} W_{ij}$$

$$P \leq [0],$$

$$P_{ij} = 0 \text{ if } \{i, j\} \notin E,$$

$$\sum_j P_{ij} = 1, \forall i.$$

Semidefinite Program(SDP)

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- Simulations on real data(cooperate with Jiefeng Li)
- Submit to INFOCOM 2018

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-  Indyk, P., 1999, May. Sublinear time algorithms for metric space problems. In Proceedings of the thirty-first annual ACM symposium on Theory of computing (pp. 428-434). ACM.
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Thank You!